

## Feature:

BT100S

- Mounts easy on round BT105S \& square shaft (with option -8).

BT120S

- External clutch for manual adjustments.

BT160S

- Maintenance free.

BT165S

- Position indicator.
- Fail safe by Enerdrive System ${ }^{1}$

BT180S
BT200S (on model 60S, 65S \& 80S).

BT205S

- Auxiliary switches
(on model 20S \& 80S).
- Reliable control for air damper applications BT260S up to $12.5 \mathrm{ft}^{2}$ [ $1.2 \mathrm{~m}^{2}$ ] (seal-less damper blades; air friction-dependent).

| Technical Data | BT100S | BT105S | BT120S | BT200S | BT205S | BT220S | BT160S | BT165S | BT180S | BT260S | BT265S | BT280S |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Auxiliary switches | No | No | Yes (2) | No | No | Yes (2) | No | No | Yes (2) | No | No | Yes (2) |
| Feedback | No | Yes | No | No | Yes | No | No | Yes | No | No | Yes | No |
| Power supply | 110 to 130 VAC $50 / 60 \mathrm{~Hz}$ |  |  | 220 to 250 VAC $50 / 60 \mathrm{~Hz}$ |  |  | 110 to 130 VAC $50 / 60 \mathrm{~Hz}$ |  |  | 220 to 250 VAC $50 / 60 \mathrm{~Hz}$ |  |  |
| Fail safe - Enerdrive | No |  |  |  |  |  | Yes |  |  |  |  |  |
| Power consumption | 6 VA |  |  |  |  |  | 20VA Peak, 6VA |  |  |  |  |  |
| Control signal | 3 wire / 2 position, 4 wire / 3 point floating |  |  |  |  |  | 2 wire / 2 position, 4 wire / 3 point floating |  |  |  |  |  |
| Ingress protection | IP22 equivalent to Nema type 2, <br> IP54 equivalent to Nema type 3R if water tight inlet bushings (not supplied NEP617) are installed |  |  |  |  |  | IP22 equivalent to Nema type 2 |  |  |  |  |  |
| Running time through 90º | 90-110 sec, (Fail-safe 20-35 sec) |  |  |  |  |  |  |  |  |  |  |  |
| Torque | $50 \mathrm{in} . \mathrm{lb}$. [ 5.6 Nm ] at rated voltage |  |  |  |  |  |  |  |  |  |  |  |
| Electrical connection | 18 AWG [0.8 mm ${ }^{2}$ ] minimum |  |  |  |  |  |  |  |  |  |  |  |
| Inlet bushing | 2 inlet bushing of 13/16 in [20.6 mm] |  |  |  |  |  |  |  |  |  |  |  |
| Angle of rotation | 0 to 90 degrees, mechanically adjustable (factory set with 90 stroke) |  |  |  |  |  |  |  |  |  |  |  |
| Direction of rotation | Reversible, Clockwise (CW) or Counterclockwise (CCW) (factory set with CW direction) |  |  |  |  |  |  |  |  |  |  |  |
| Ambient temperature | $-22^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.50^{\circ} \mathrm{C}\right]$ |  |  |  |  |  |  |  |  |  |  |  |
| Storage temperature | $-22^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}$ [ $-30^{\circ} \mathrm{C}$ to $50^{\circ} \mathrm{C}$ ] |  |  |  |  |  |  |  |  |  |  |  |
| Relative Humidity | 5 to $95 \%$ non condensing. |  |  |  |  |  |  |  |  |  |  |  |
| Weight | $3 \mathrm{lbs} .[1.4 \mathrm{~kg}$ ] |  |  |  |  |  |  |  |  |  |  |  |
| Warning: Do not press the clutch when actuator is powered |  |  |  |  |  |  |  |  |  |  |  |  |

## Dimensions



## Caution

We strongly recommend that all Neptronic ${ }^{(\pi)}$ products be wired to a separate transformer and that transformer shall service only Neptronic ${ }^{(\pi)}$ products. This precaution will prevent interference with, and/or possible damage to incompatible equipment.
When multiple actuators are wired on a single transformer, polarity must be observed. Long wiring runs create voltage drop which may affect the actuator performance.

[^0]
## Mechanical Installation



1. Manually close the damper blades and positioned the actuator at $0^{\circ}$ or $90^{\circ}$.
2. Slide the actuator onto the shaft.
3. Tighten the nuts on the " $U$ " bolt to the shaft with a 8 mm wrench to a torque of 60 in . lb . [6,7 Nm].
4. Slide the mounting bracket under the actuator. Ensure free movement of the slot at the base of the actuator. The bracket pin must be placed in the mid distance of the slot.
5. Fix the bracket to the ductwork with \#8 self-tapping screws.

## Wiring Diagrams

## Caution: Risk of electric shock. Remove power prior to connect.



## PC Board

|  | Dip switch settings <br> Rotation direction (SW1) <br> CW <br> (0 to $90^{\circ}$ ) $\square$ |  |
| :---: | :---: | :---: |
|  | Fail safe direction (SW2) <br> Fail safe return at $0^{\circ}$ $\square$ | Fail safe return at $90^{\circ}$ |

## Stroke Adjustment

To adjust the stroke, move the adjustment screws at the desired position.


[^0]:    ${ }^{1}$ Enerdrive System U.S.A. Patent \#5,278,454

